

Performance Engineering and Debugging HPC Applications

David Skinner

deskinner@lbl.gov









Nerse Today: Tools for Performance and Debugging

Principles

- Topics in performance scalability
- Examples of areas where tools can help

Practice

- Where to find tools
- Specifics to NERSC and Hopper







Big Picture of Scalability and Performance



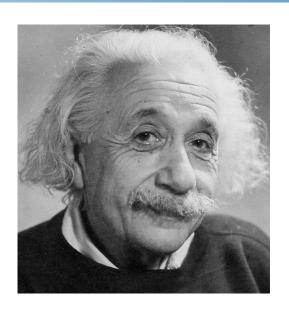




Performance is Relative

To your goals

- Time to solution, T_{queue}+T_{run}
- Your research agenda
- Efficient use of allocation



To the

- application code
- input deck
- machine type/state

Suggestion:
Focus on specific use cases as opposed to making everything perform well.

Bottlenecks can shift.







Performance is Hierarchical

Registers

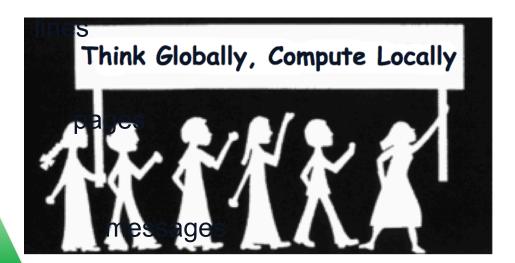
instructions & operands

Caches

Local Memory

Remote Memory

Disk / Filesystem



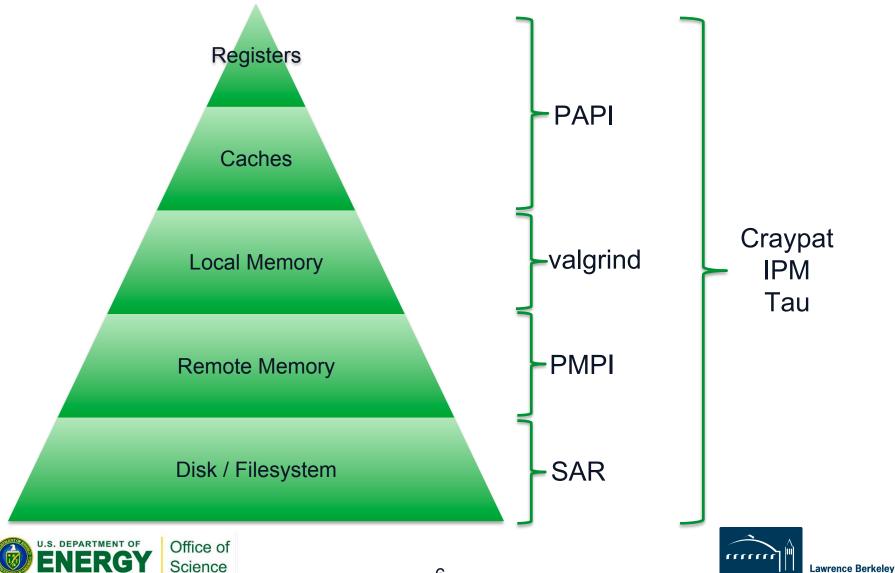
blocks, files







Tools are Hierarchical



National Laboratory



Using the right tool

Tools can add overhead to code execution

What level can you tolerate?

Tools can add overhead to scientists

What level can you tolerate?

Scenarios:

- Debugging code that ~isn't working
- Performance debugging
- Performance monitoring in production







One tool example: IPM on XE

- 1) Do "module load ipm", link with \$IPM, then run normally
- 2) Upon completion you get

Maybe that's enough. If so you're done.

Have a nice day ☺







HPC Tool Topics

CPU and memory usage

- FLOP rate
- Memory high water mark

OpenMP

- OMP overhead
- OMP scalability (finding right # threads)

MPI

- % wall time in communication
- Detecting load imbalance
- Analyzing message sizes







Examples of HPC tool usage







Scaling: definitions

- Scaling studies involve changing the degree of parallelism. Will we be change the problem also?
- Strong scaling
 - Fixed problem size
- Weak scaling
 - Problem size grows with additional resources
- Speed up = $T_s/T_p(n)$
- Efficiency = $T_s/(n^*T_p(n))$

Be aware there are multiple definitions for these terms







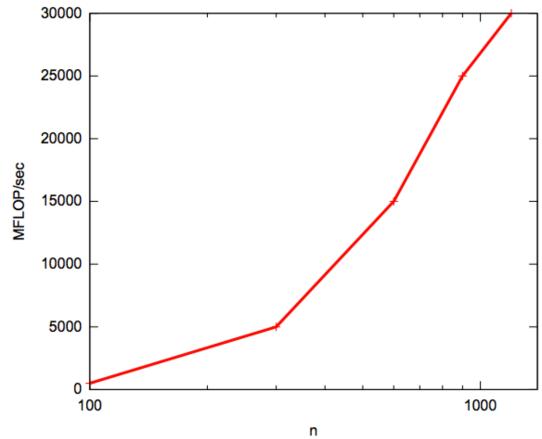
Conducting a scaling study

With a particular goal in mind, we systematically vary concurrency and/or problem size

Example:

How large a 3D (n^3) FFT can I efficiently run on 1024 cpus?

Looks good?









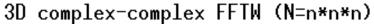
Let's look a little deeper....

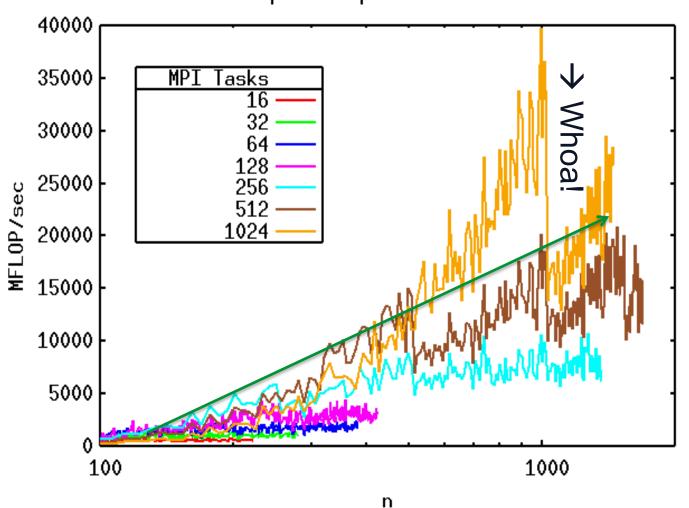






The scalability landscape





Why so bumpy?

- Algorithm complexity or switching
- Communication protocol switching
- Inter-job contention
- ~bugs in vendor software

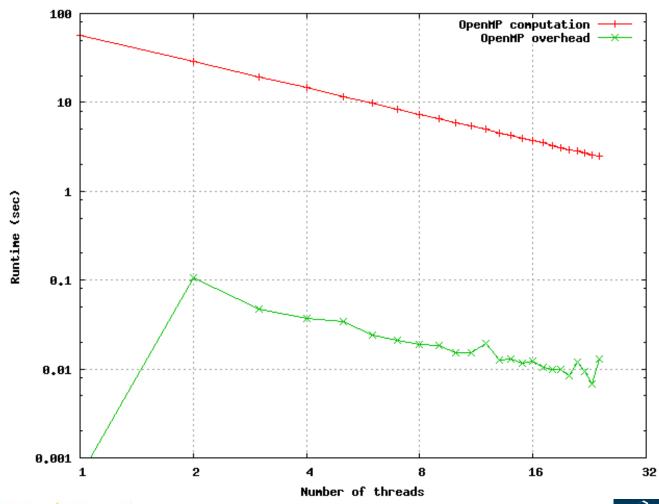






Not always so tricky

Main loop in jacobi_omp.f90; ngrid=6144 and maxiter=20



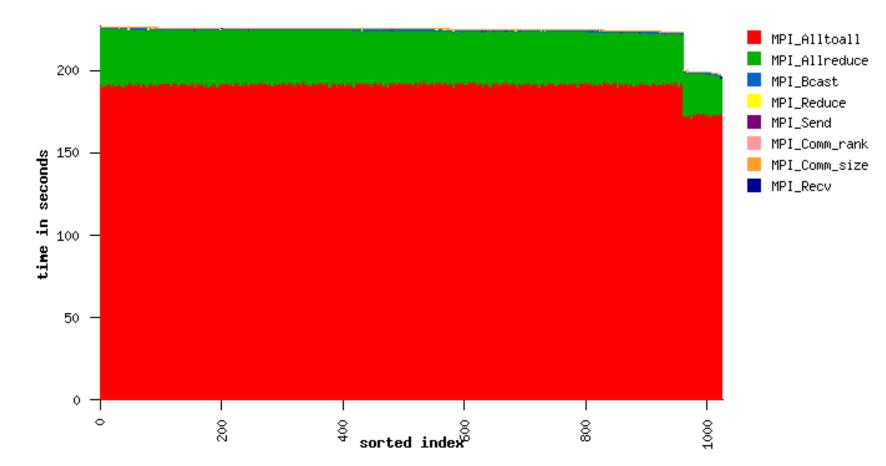






Load (Im)balance

Communication Time: 64 tasks show 200s, 960 tasks show 230s



MPI ranks sorted by total communication time

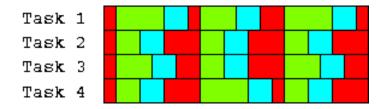






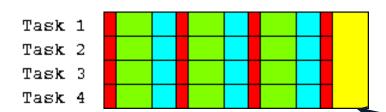
Load Balance: cartoon

Unbalanced:



Universal App Sync Flop I/0

Balanced:



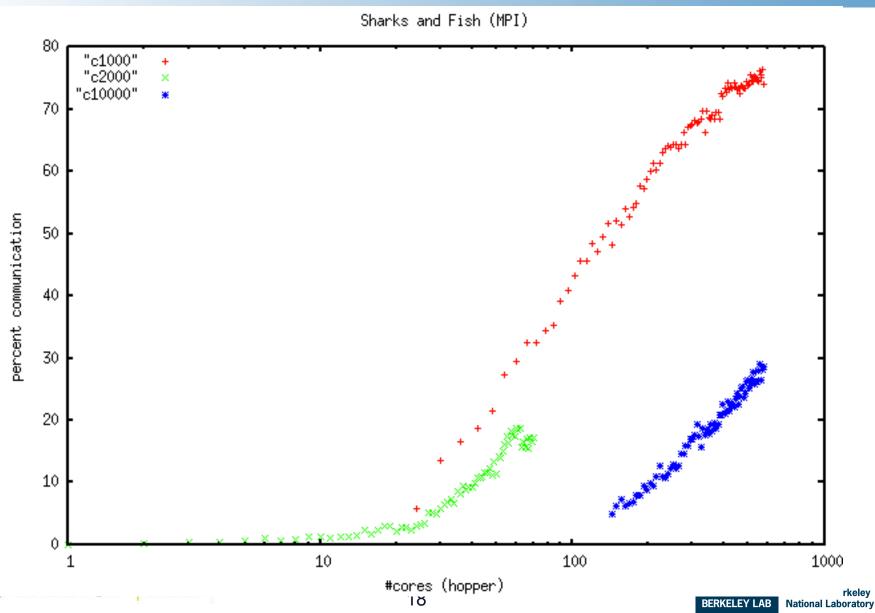
Time saved by load balance





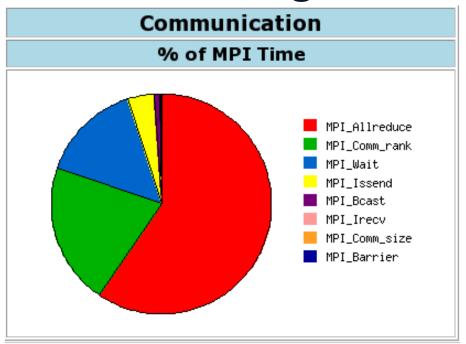


Too much communication





Simple Stuff: What's wrong here?



Communication Event Statistics (100.00% detail)

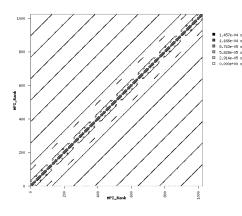
	Buffer Size	Ncalls	Total Time	Min Time	Max Time	%MPI	%Wall
MPI_Allreduce	8	3278848	124132.547	0.000	114.920	59.35	16.88
MPI_Comm_rank	0	35173439489	43439.102	0.000	41.961	20.77	5.91
MPI_Wait	98304	13221888	15710.953	0.000	3.586	7.51	2.14
MPI_Wait	196608	13221888	5331.236	0.000	5.716	2.55	0.72
MPI_Wait	589824	206848	5166.272	0.000	7.265	2.47	0.70



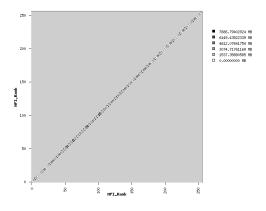




Not so simple: Comm. topology

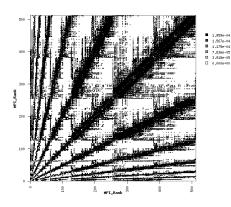


MILC

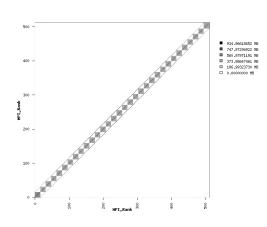


PARATEC

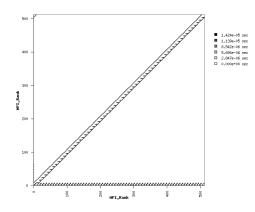




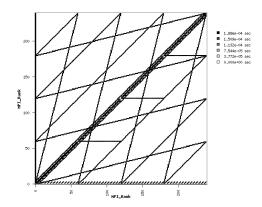
MAESTRO



IMPACT-T



GTC







The state of HW counters

- The transition to many-core has brought complexity to the once orderly space of hardware performance counters. NERSC, UCB, and UTK are all working on improving things
- IPM on XE, currently just the banner is in place. We think PAPI is working (recently worked with Cray on bug fixes)







Next up...Richard.



